

FIG. 1

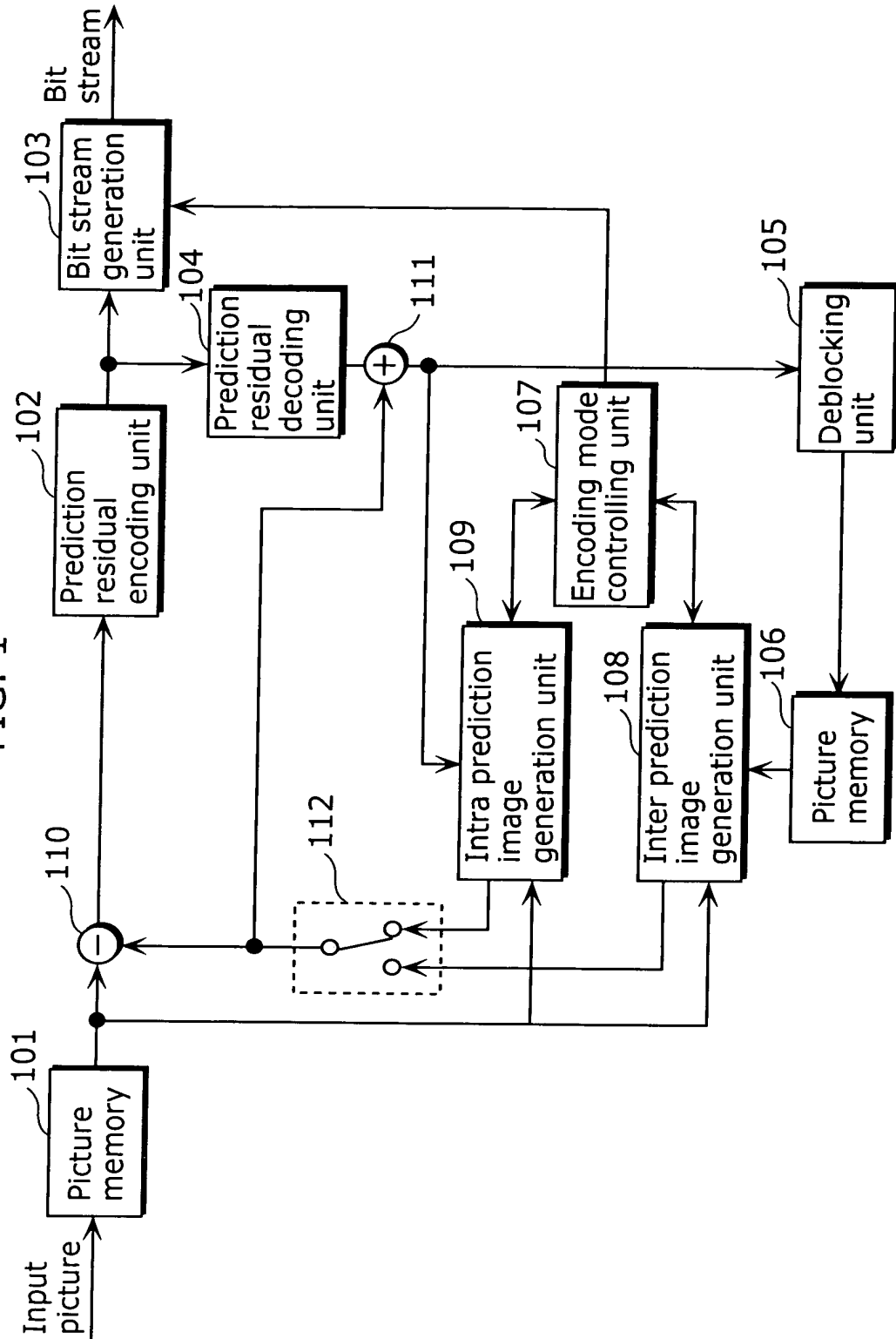
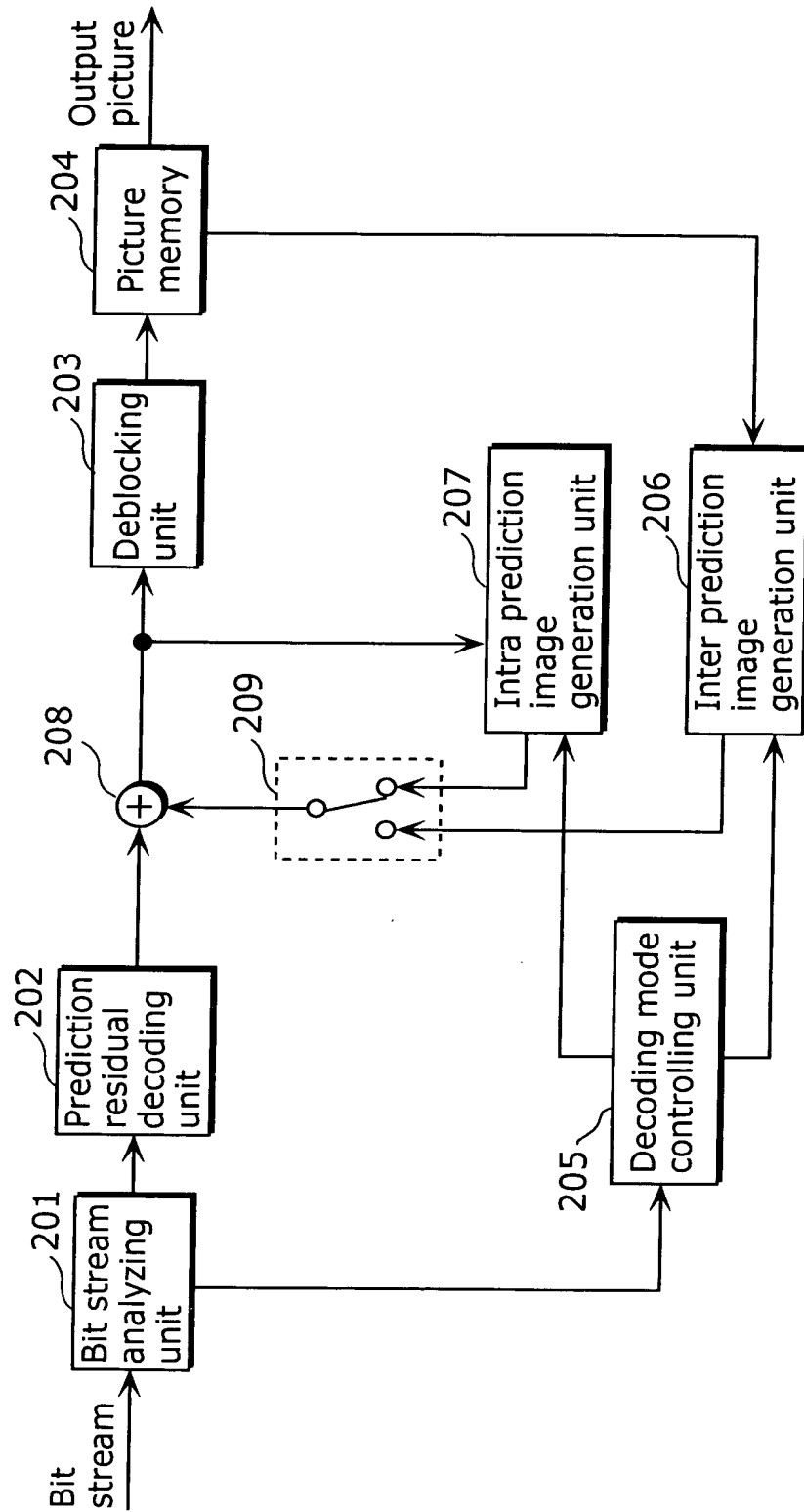


FIG. 2



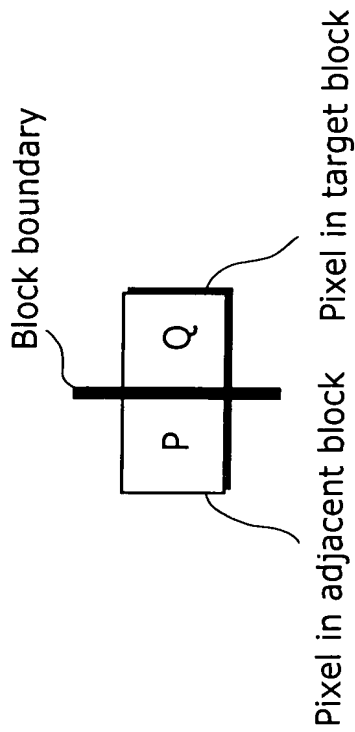


FIG. 3A

Filter 4	In the case where a boundary is at vertical edge and either P or Q belongs to block which is intra prediction encoded.
Filter 3	In the case where a boundary is at horizontal edge and either P or Q belongs to a block which is intra prediction encoded.
Filter 2	In the case where either P or Q belongs to a block having coefficient other than 0.
Filter 1	In the case where P and Q belong to a block which is inter prediction encoded and refer to respective pictures, or refer using respective motion vectors.
Filter 0	Other than the above.

FIG. 3B

FIG. 4

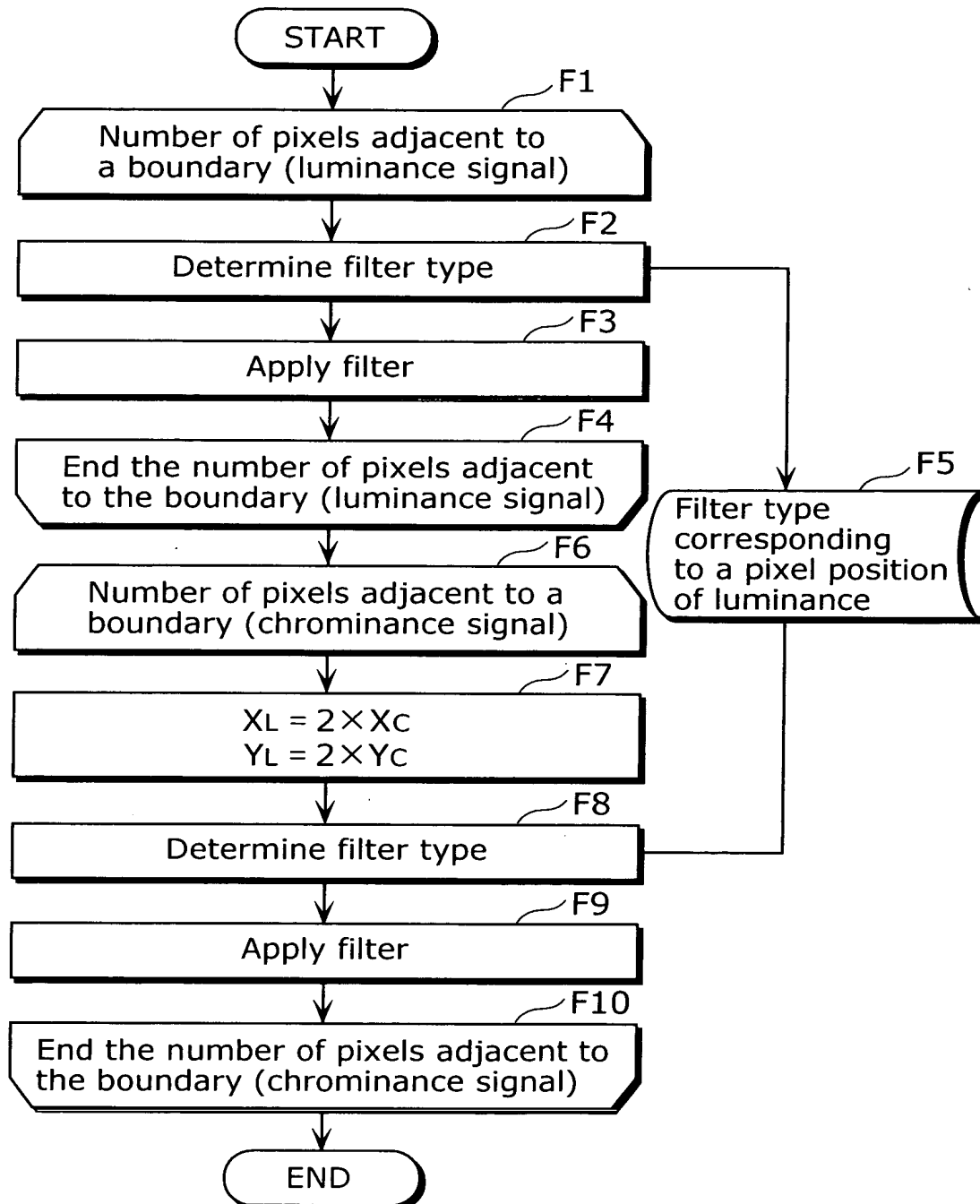


FIG. 5A

Half decimation in
horizontal and vertical
directions

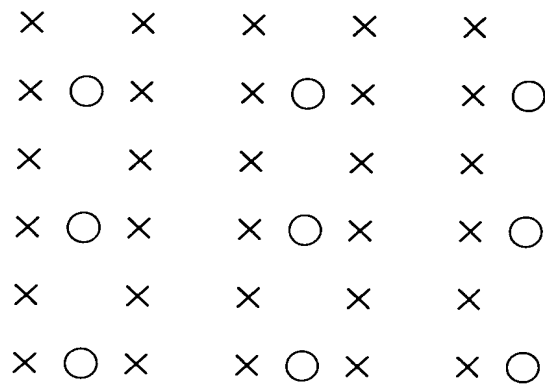


FIG. 5B

Half decimation in
horizontal direction

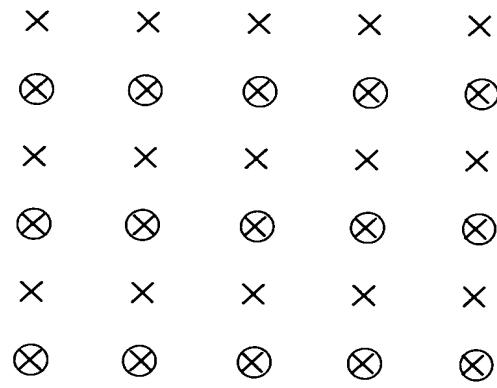


FIG. 5C

No decimation

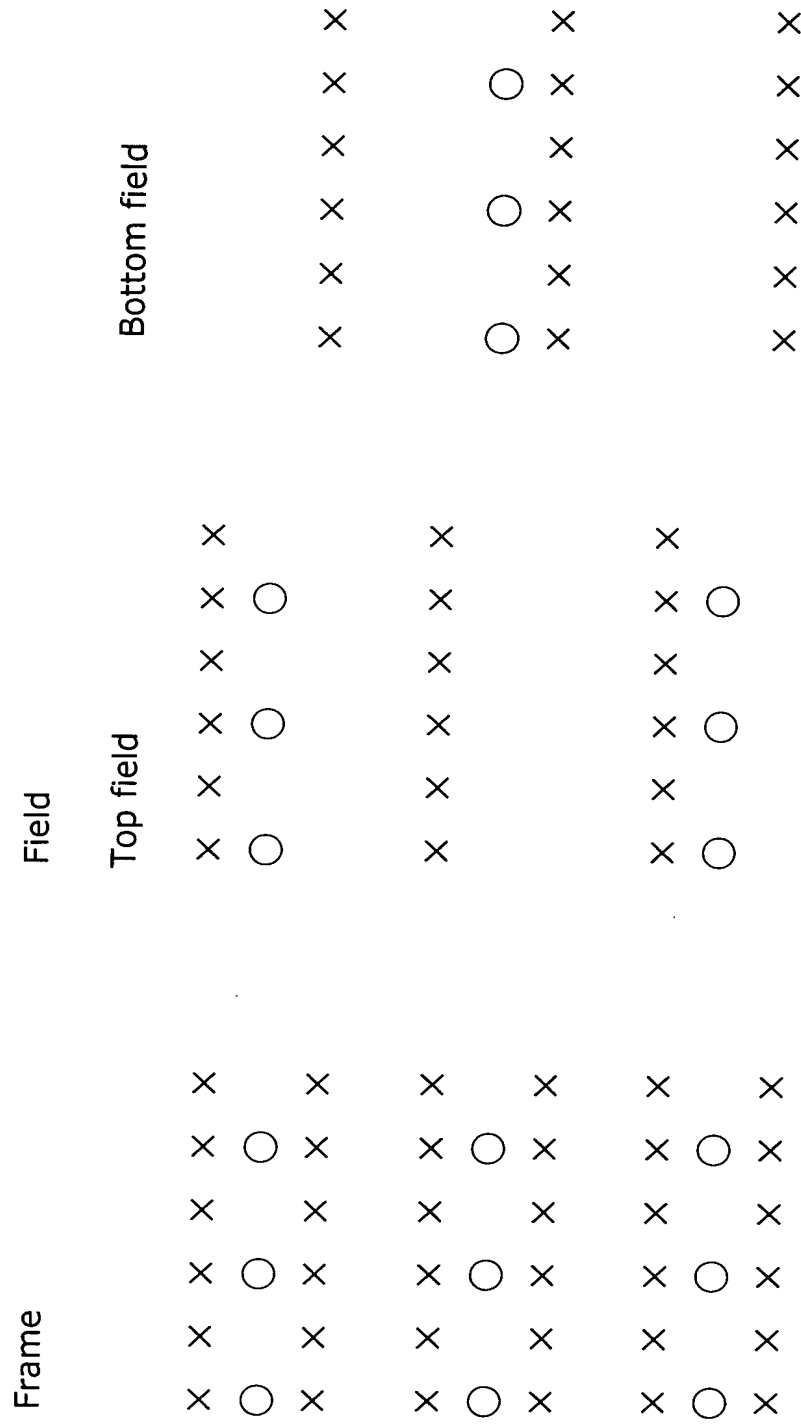


X : Luminance component sample position

O : Chrominance component sample position

FIG. 6A

FIG. 6B



X : Luminance component sample position
 O : Chrominance component sample position

FIG. 7A

FIG. 7B

Frame

Field

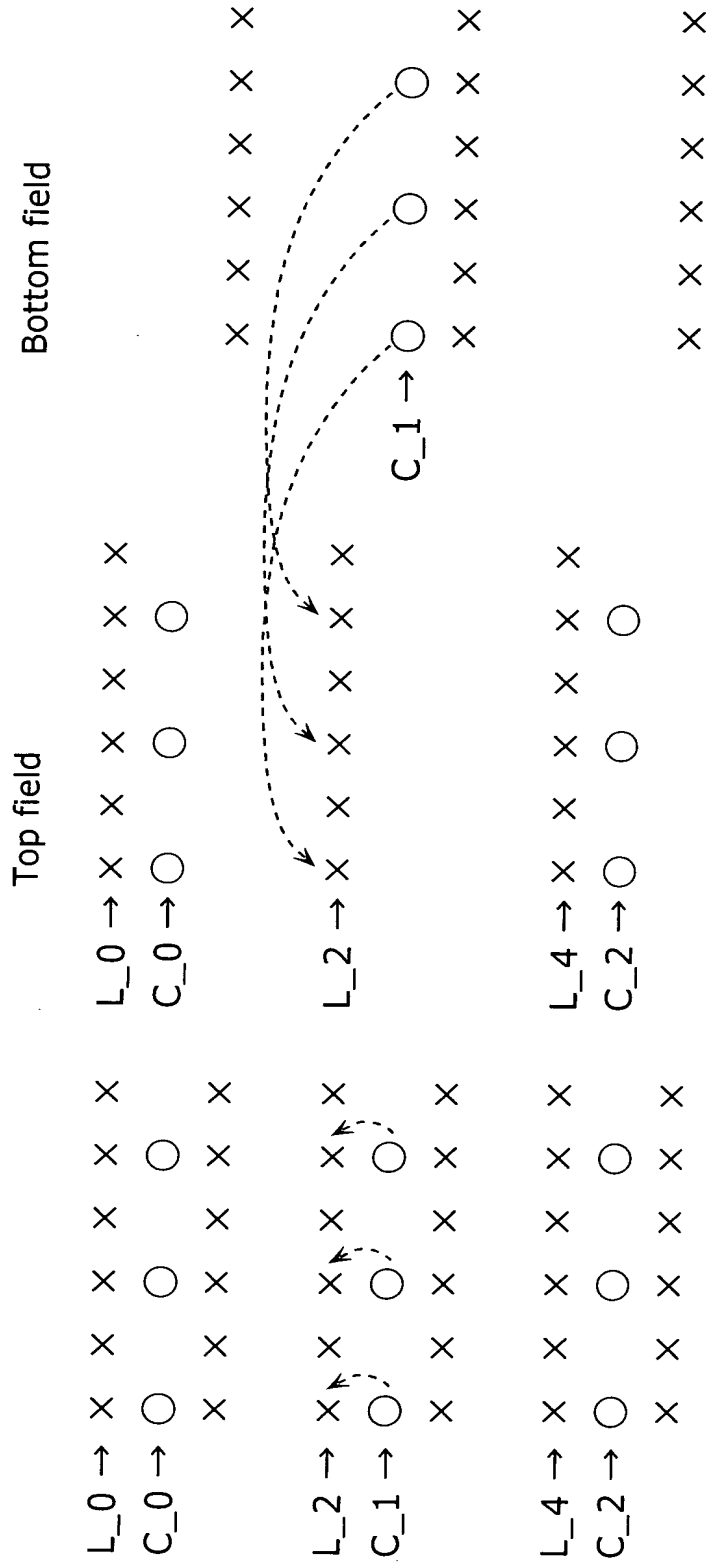


FIG. 8

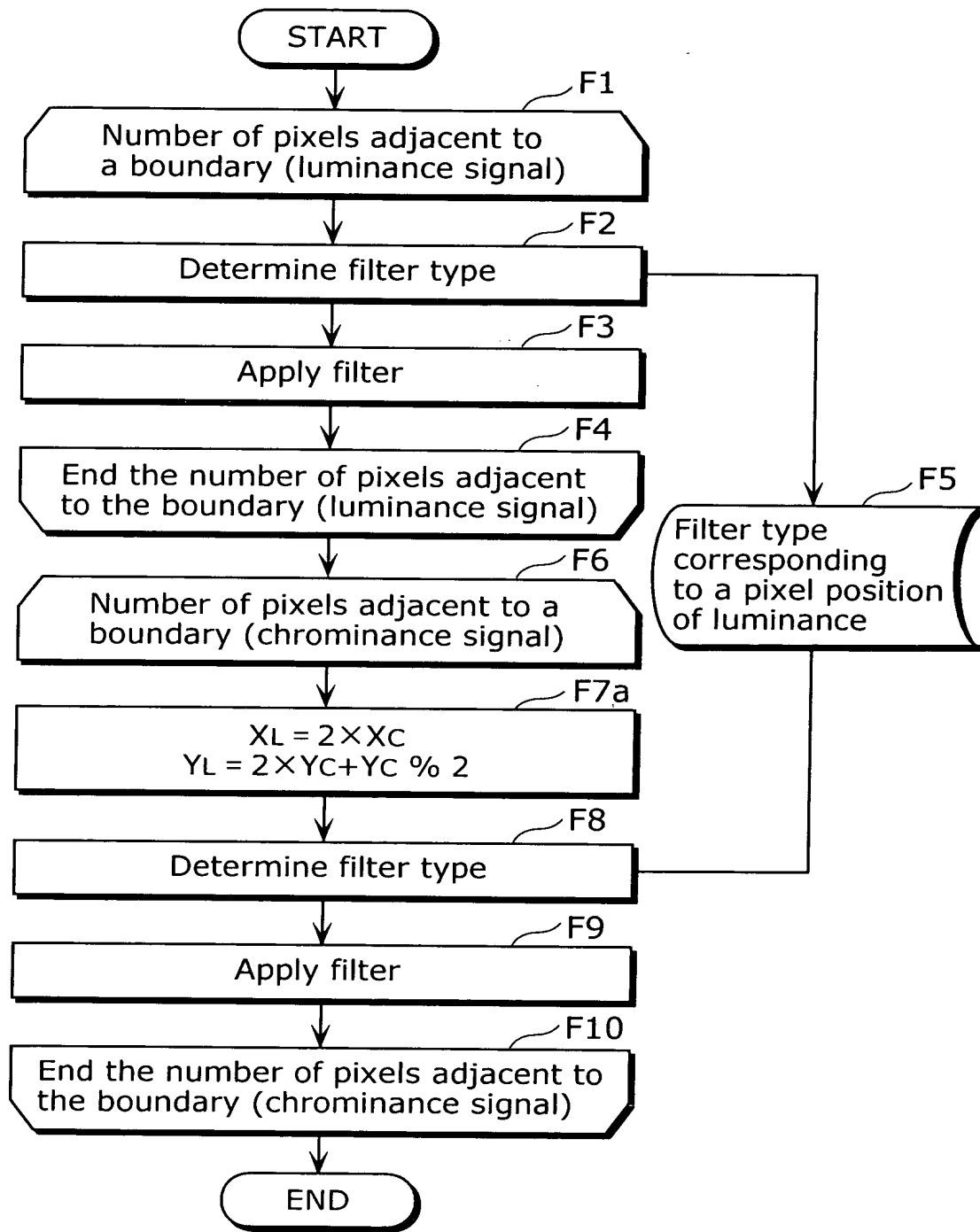


FIG. 9A
Frame

FIG. 9B
Field

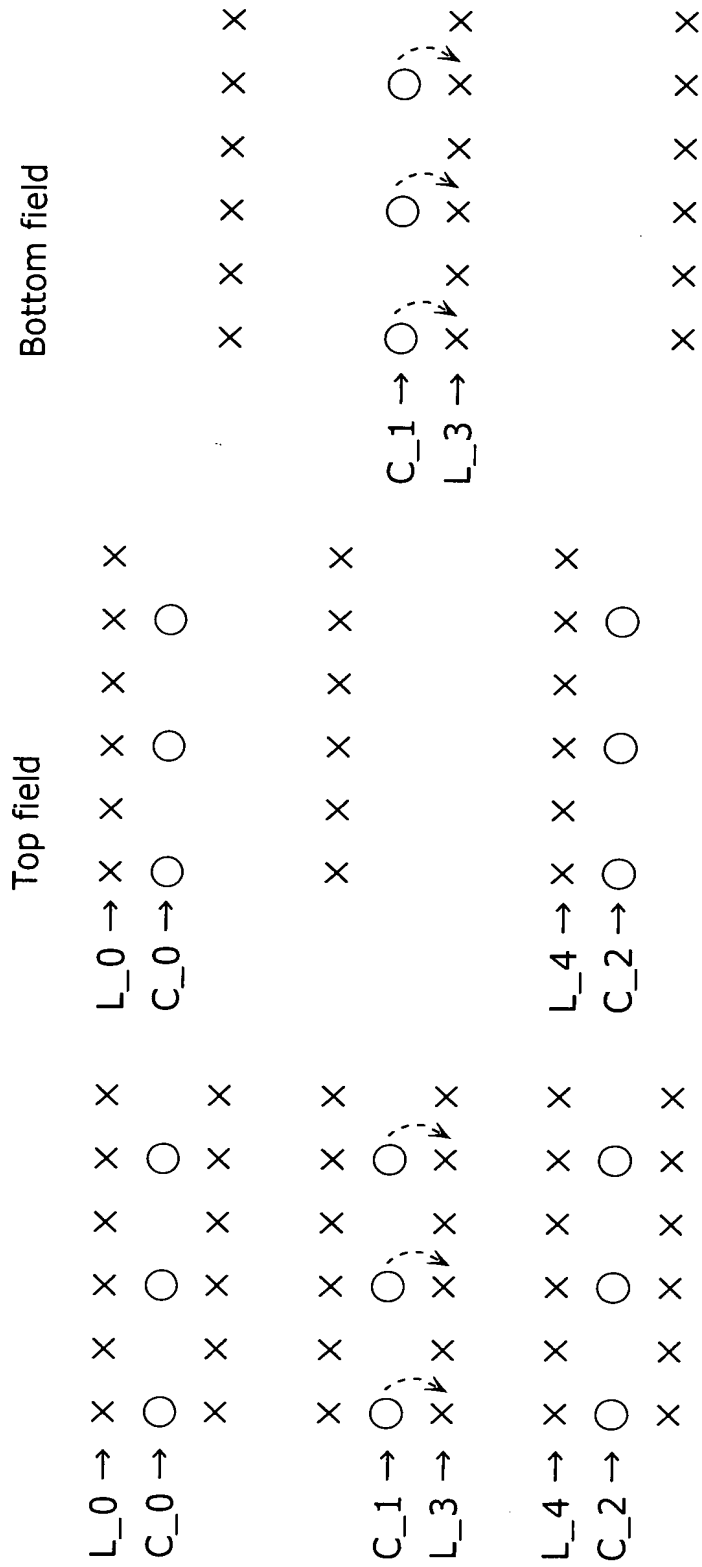


FIG. 10A

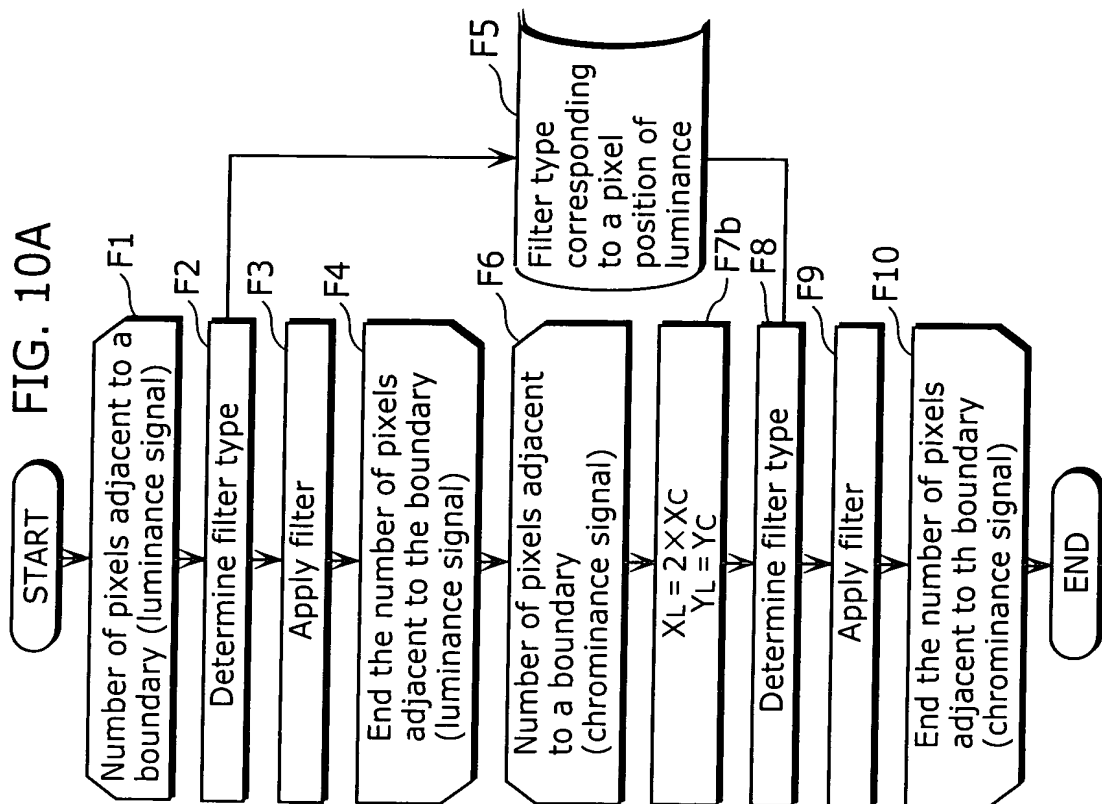


FIG. 10B

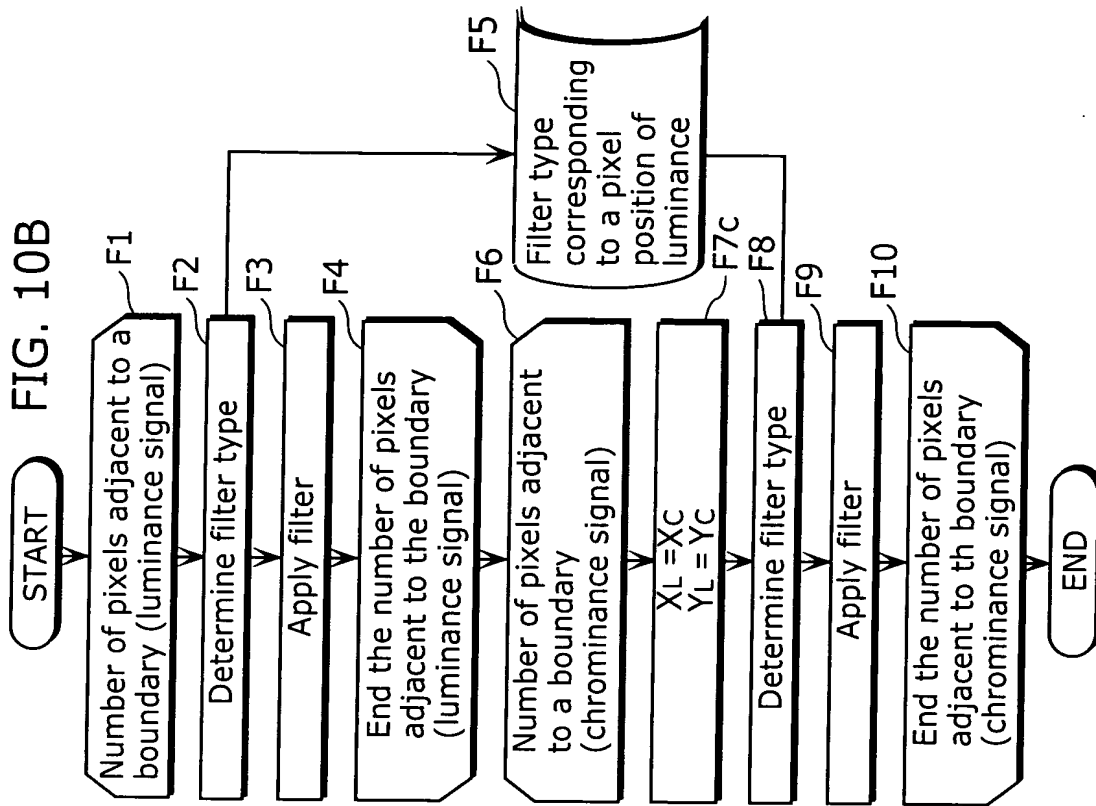
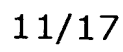


FIG. 11B



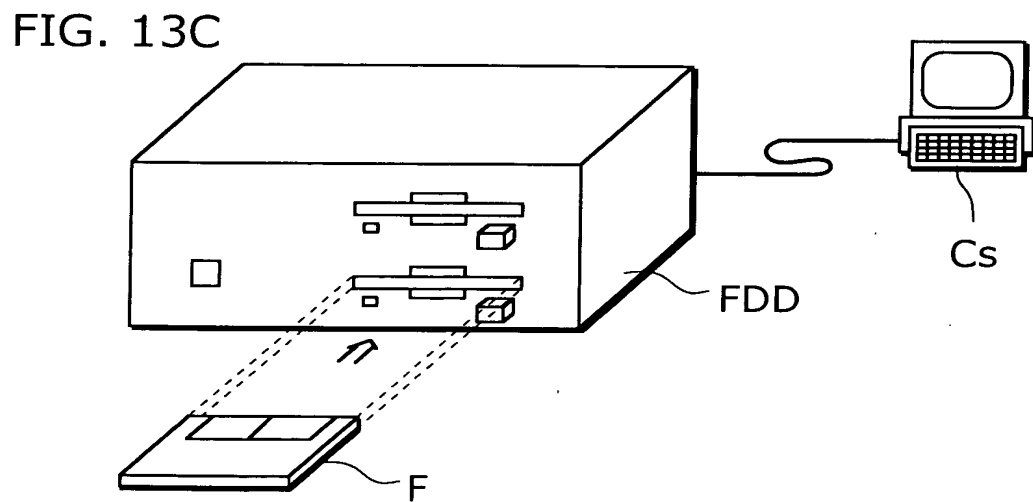
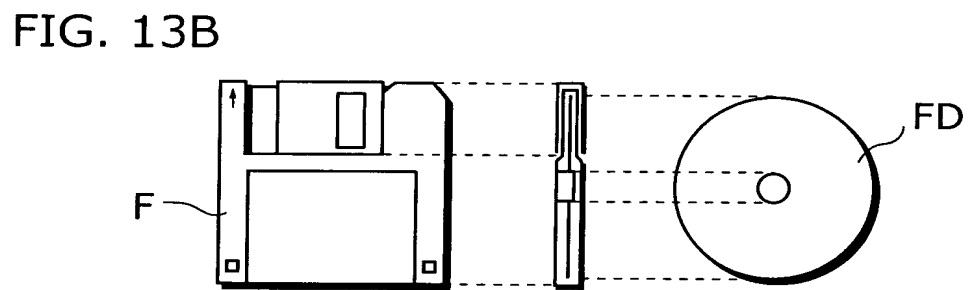
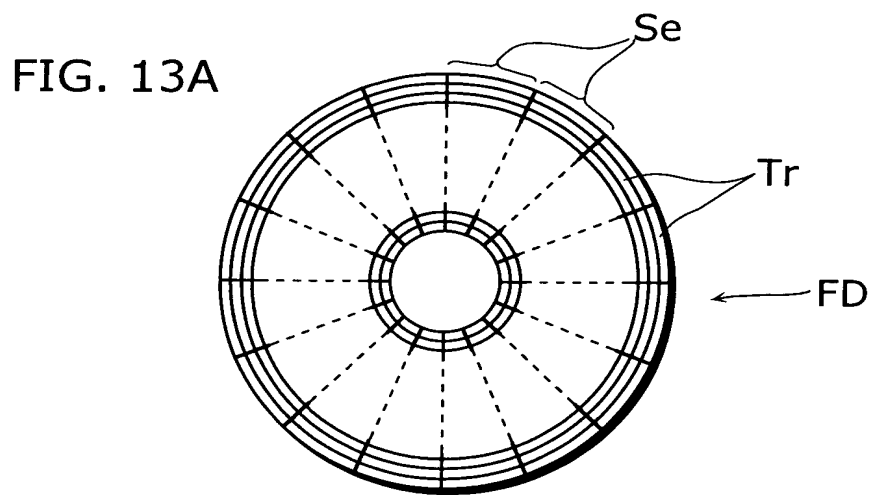


FIG. 14

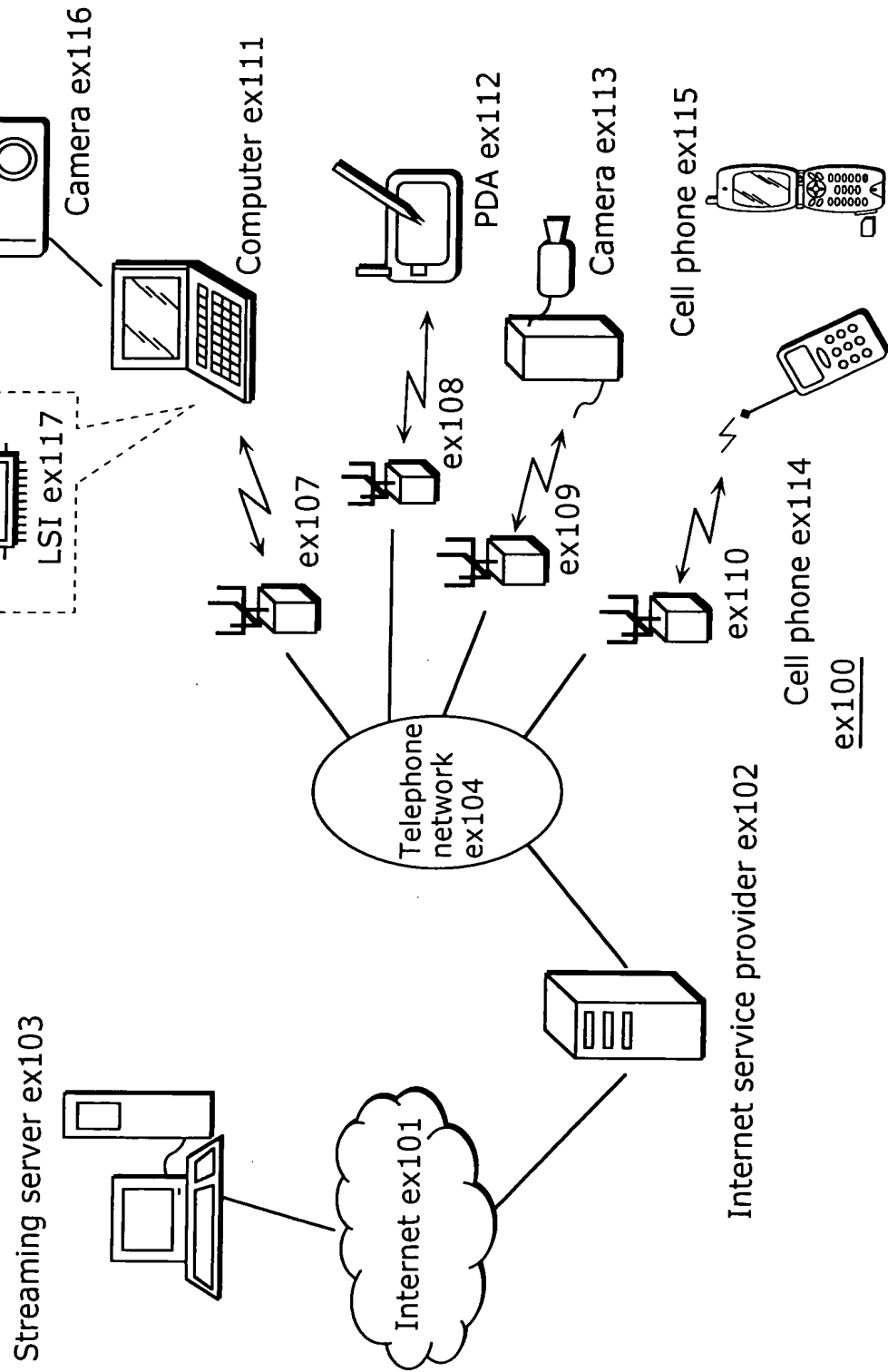


FIG. 15

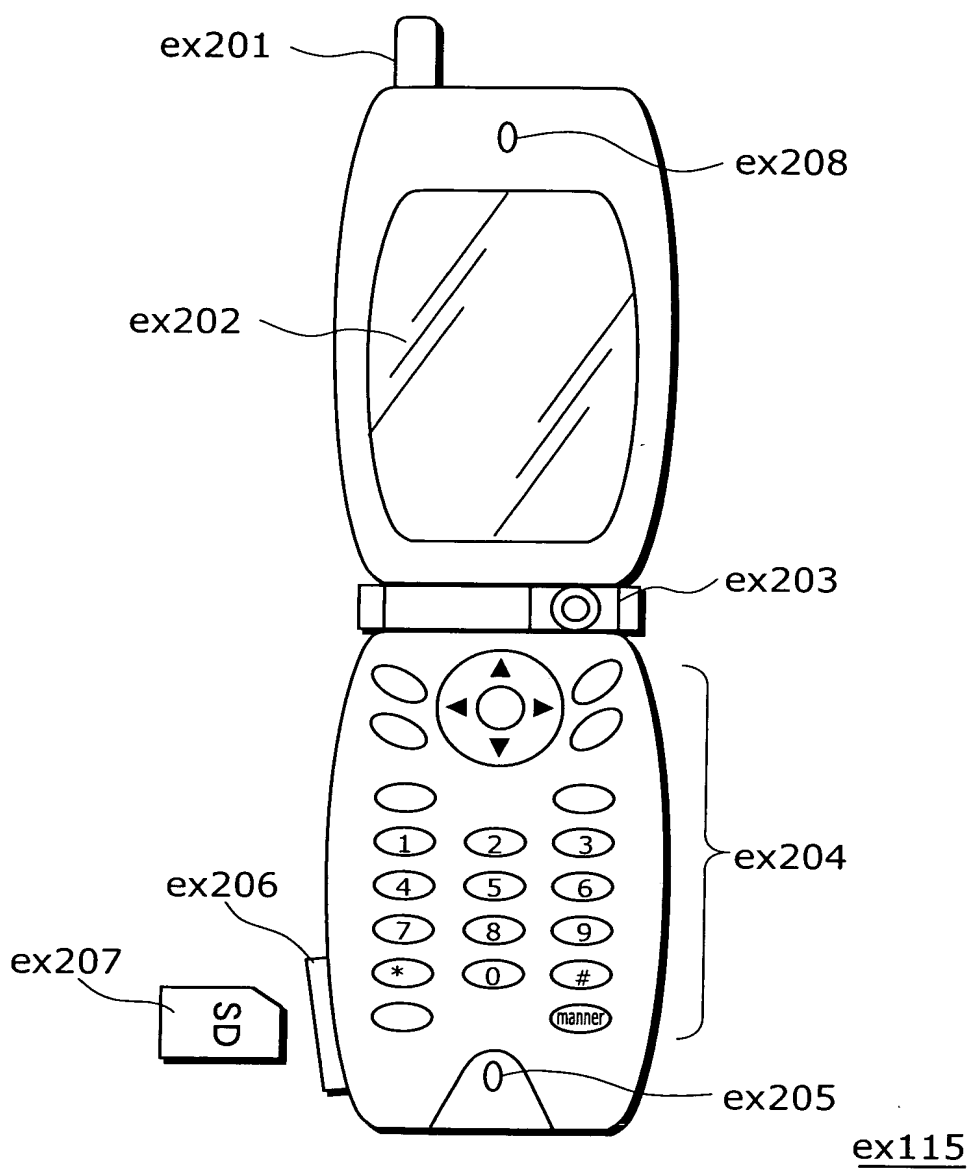


FIG. 16

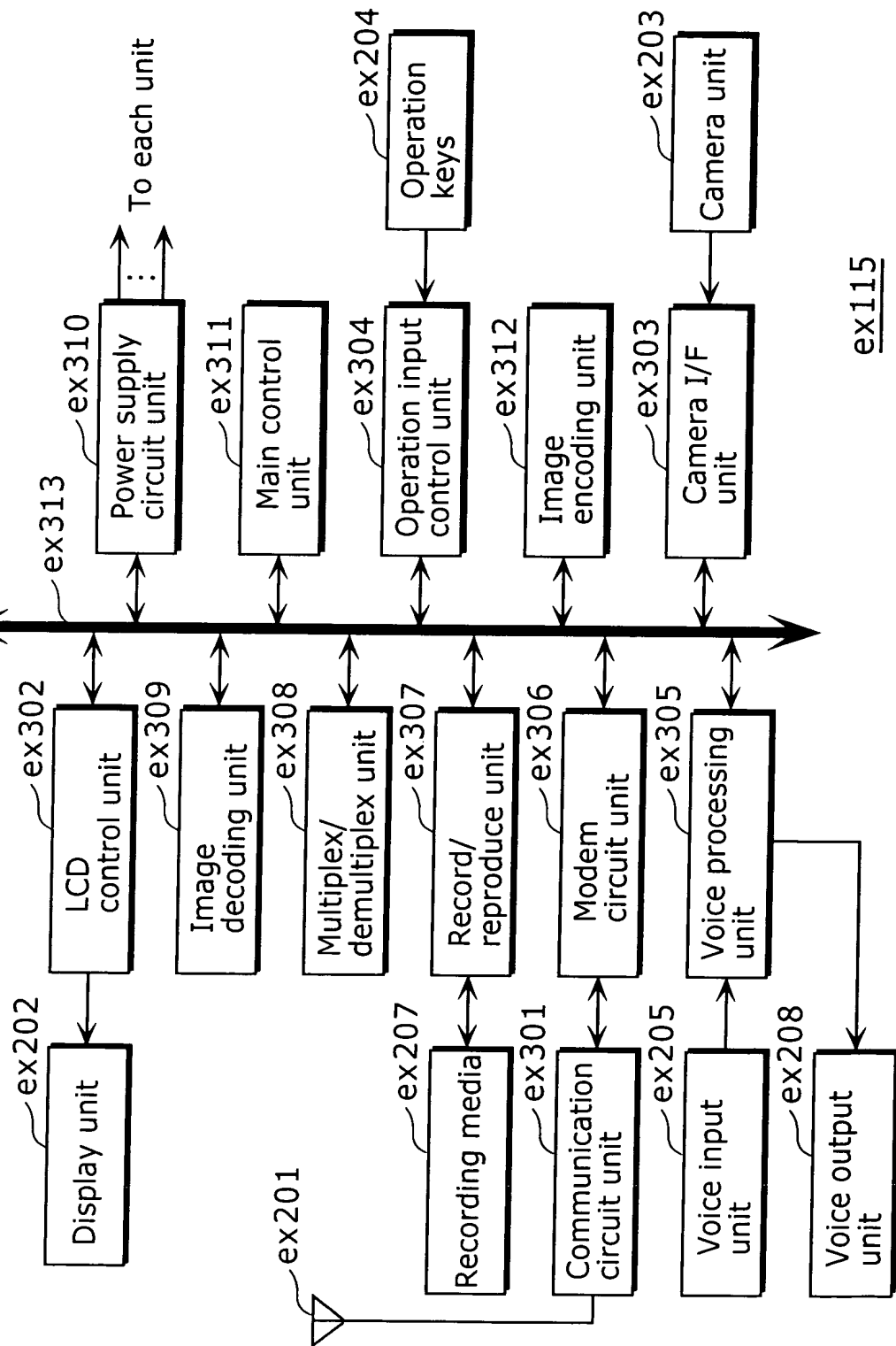


FIG. 17

